

INDOOR MOBILE ROBOT LOCALIZATION

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Indoor localization becomes one of the most important part in mobile robot system One fundamental requirement is to provide an easy-to-use and practical.

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However, the summed signal may appear incoherent due to the inconsistent signal phase of each antenna. Kohlhepp, P. The antenna weights are set as one.

Figure 9d shows the result of self-localization based only on odometry. Vaskevicius, M. Communications of the ACM, 24 6 – Shao, F. Guerrieri J. Figure 1.